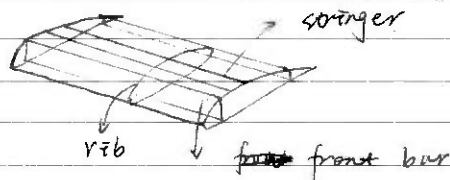


1. (a)



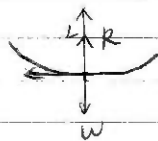
- ① front bar and rear bar. They are the final load carrier of the wing
- ② skin. The main purpose of skin is for good aerodynamic performance. But they are still integrated to carry load
- ③ stringer. It prevents skin buckling
- ④ rib. It increases wing stiffness

(b) ① flap. high lift device which increases lift through increase effective angle of attack.

② slot. high lift device which increase lift through increase wing area and delay flow separation

③ spoiler. high drag devices which helps in landing

(c)



$$L - W = \frac{mv^2}{R} = \frac{Wv^2}{gR}$$

$$n = \frac{L}{W}$$

$$\Rightarrow n - 1 = \frac{v^2}{gR}$$

$$R = \frac{v^2}{g(n-1)}$$

$$R_{\min} = \frac{v^2}{g(A_{\max}-1)} = \frac{400^2}{g(1.5-1)} = 1304.8 \text{ (m)}$$

(d) $L = \frac{1}{2} \rho u_{\infty}^2 S C_L$

$$\Delta L = \frac{1}{2} \rho u_{\infty}^2 S \frac{dC_L}{dx} \cdot \Delta x$$

due to the downwash

$$\Delta x = -\frac{u}{u_{\infty}} = -0.06$$

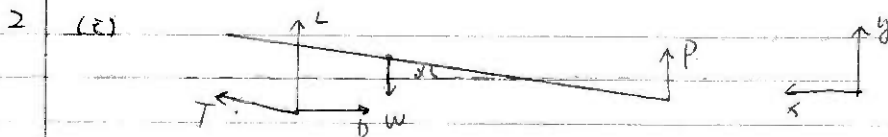
$$\therefore \Delta L = \frac{1}{2} \times \rho \times 150^2 \times S \times 5 \times (-0.06) = -3375 \text{ ps}$$

$$\sum F = L_{\text{new}} - W = ma$$

$$a = \frac{L_{\text{new}} - W}{m} = \frac{(L_{\text{steady}} - \Delta L) - W}{m}$$

$$W = L_{\text{steady}} = \frac{1}{2} \rho u_{\infty}^2 S C_L = 2025 \text{ ps}$$

$$\Rightarrow a = -16.35 \text{ (kg/s}^2\text{)}$$



During steady level flight

the angle of attack is α .

$$\sum F_x = T \cos \alpha - D = ma_x = 0$$



$$L = \frac{1}{2} \rho_0 u_\infty^2 S C_L \Rightarrow C_L = 0.295$$

$$C_D = 0.02 + 0.04 C_L^2 = 0.02348$$

$$D = \frac{1}{2} \rho_0 u_\infty^2 S C_D = 28716 \text{ (N)}$$

$$M_0 = \frac{1}{2} \rho_0 u_\infty^2 S \bar{c} C_{m_0} = -158990 \text{ (Nm)}$$

$$\sum M_{cg} = L(6.5) + M_0 - D(0.4) - p(8.5) = 0$$

$$\therefore p = 1195.3$$

$$\therefore \text{Lift } L = 361273.7 \text{ (N)}$$

$$p = 1195.3 \text{ (N)}$$

$$(iii) \quad \sum F_x = T - D = 0 \Rightarrow T = D = \frac{1}{2} \rho_0 u_\infty^2 S (0.02 + 0.04 C_L^2) \dots$$

$$\sum F_y = L + p = nW \Rightarrow L = nW - p \dots \dots \dots \textcircled{1}$$

$$\sum M_{cg} = L(6.5) + T(6.4) + M_0 - D(0.4) - p(8.5) = 0 \dots \dots \textcircled{2}$$

$$M_0 = \frac{1}{2} \rho_0 u_\infty^2 S \bar{c} C_{m_0} = -3.97 u_\infty^2 \dots \dots \dots \textcircled{3}$$

$$\sum F_y = L + p + T \sin \alpha - w = 0$$

$$\sum M_{cg} = L \cos \alpha (0.5) + L \sin \alpha (0.4) + T \cdot 0.4 + M_0$$

$$- D \cos \alpha (0.4) + D \sin \alpha (0.5) - p \cos \alpha (8.5) = 0$$

If α is considered as small angle.

$$\sin \alpha = 0, \quad \cos \alpha = 1$$

$$\sum F_x = T - D = 0$$

$$\sum F_y = L + p - w = 0$$

$$\sum M_{cg} = L \cdot (0.5) + T \cdot (0.4) + M_0 - D \cdot (0.4) - p \cdot 8.5 = 0$$

$$(ii) \quad \sum F_y = L + p = n w$$

$$\text{since } L \gg p \quad \therefore L = n w = \frac{1}{2} \rho_0 U_0^2 S C_L$$

$$\Rightarrow C_L = 0.2 p b$$

$$C_D = 0.02 + 0.04 C_L^2 = 0.0235$$

$$\therefore D = \frac{1}{2} \rho_0 U_0^2 S C_D = 28740.5 \text{ (N)}$$

$$M_0 = \frac{1}{2} \rho_0 U_0^2 S C M_0 = -158990 \text{ (Nm)}$$

$$\sum M_{cg} = L (0.5) + M_0 - D (0.4) - p \cdot 8.5 = 0$$

$$p = 1266.3 \text{ (N)}$$

Iteration •

$$\sum F_y = L + p = n w \Rightarrow L = n w - p = 361273.7 \text{ (N)}$$

From ① ② ③ ④

$$(11W - p) \times 0.5 - 3.97 U_0^2 - 8.5p = 0$$

$$p = 8055 \text{ N} - 0.44 U_0^2$$

the bending moment about cg is

$$M_b = 11M_{\text{steady}} - 8.5p$$

$$M_{\text{CG-steady}} = M_{\text{steady}} - 8.5p = 300000$$

$$P_{\text{steady}} = 8055 \times 1 - 0.44 \times 250^2 = -19445 \text{ (W)}$$

$$\therefore M_{\text{steady}} = 280563.5 \text{ (Wm)}$$

$$\therefore M_b = 280563.5 \text{ N} - 8.5 \times (8055 \text{ N} - 0.44 U_0^2)$$

$$= 212096.5 \text{ N} + 3.74 U_0^2$$

check the corner point

At point C

$$r_c = 4 \quad V_c = 250$$

$$M_{b-c} = 1082136 \text{ (Wm)}$$

At point D₁

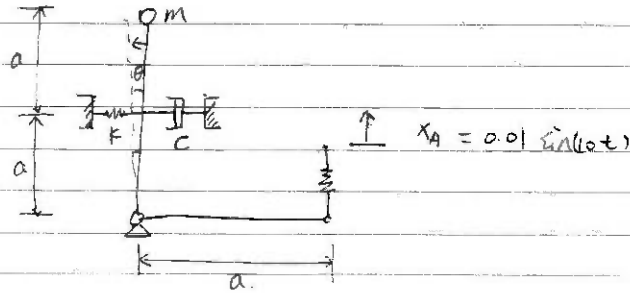
$$r_{D_1} = 2.5 \quad V_{D_1} = 300$$

$$M_{b-D_1} = 866841.25 \text{ (Wm)}$$

\therefore the maximum bending moment is at point C

$$M_{b-\text{max}} = 1082136 \text{ (Wm)}$$

3 (i)



$$\sum M = mg \cdot \theta \cdot (2a) - k \cdot \theta a \cdot a - c \dot{\theta} a \cdot a - k(a\theta - x_A) \cdot a = I \ddot{\theta}$$

$$I = m(2a)^2 = 0.64$$

$$\therefore 0.64 \ddot{\theta} + 0.16 \dot{\theta} + 30.55 \theta = 0.48 \sin(10t)$$

$$(ii) \omega_n = \sqrt{\frac{k_e}{m_e}} = \sqrt{\frac{30.55}{0.64}} = 6.9 \text{ (rad/s)}$$

$$\zeta = \frac{c}{2\sqrt{mk}} = \frac{0.16}{2\sqrt{0.64 \times 30.55}} = 0.018$$

$$(iii) Q = \frac{1}{2\zeta} = \frac{1}{2 \times 0.018} = 27.78$$

$$M = \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} = \frac{Q}{\sqrt{2}} = \frac{1}{2\sqrt{2}\zeta} \Rightarrow$$

$$r_1 = \sqrt{1 - 2\zeta^2 - 2\zeta \sqrt{1 + \zeta^2}} = 0.9815$$

$$r_2 = \sqrt{1 - 2\zeta^2 + 2\zeta \sqrt{1 + \zeta^2}} = 1.018$$

$$\therefore \Delta \omega = (r_2 - r_1) \omega_n = 0.252 \text{ (rad/s)}$$

(iv) For Equation of motion

$$0.64 \ddot{\theta} + 0.16 \dot{\theta} + 30.55 \theta = 0.48 \sin(10t)$$

The general solution is

$$\theta = \theta_0 \sin(10t - \phi)$$

$$\left. \begin{aligned} \theta_0 &= \frac{0.48}{30.55} \cdot \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} \\ r &= \frac{\omega}{\omega_n} = \frac{10}{6.9} = 1.45 \end{aligned} \right\} \Rightarrow \theta_0 = 0.014$$

$$\phi = \tan^{-1} \left(\frac{2\zeta r}{1-r^2} \right) = -2.71^\circ$$

\(\therefore\) steady state response \(\theta(t)\) is

$$\theta(t) = 0.014 \cdot \sin(10t - 2.71^\circ)$$

4 (i) For m_1 ,

$$\sum F = -k_1 x_1 - k_2(x_1 - x_2) = m_1 \ddot{x}_1 \quad \dots \dots \dots \textcircled{1}$$

For m_2 ,

$$\sum F = F_2 - k_2(x_2 - x_1) = m_2 \ddot{x}_2 \quad \dots \dots \dots \textcircled{2}$$

$$\text{let } x_1 = A_1 \sin(\omega t) \Rightarrow \ddot{x}_1 = -A_1 \omega^2 \sin(\omega t) \quad \dots \dots \dots \textcircled{3}$$

$$x_2 = A_2 \sin(\omega t) \Rightarrow \ddot{x}_2 = -A_2 \omega^2 \sin(\omega t) \quad \dots \dots \dots \textcircled{4}$$

From \textcircled{1} \textcircled{2} \textcircled{3} \textcircled{4}

$$(m_1 \omega^2 - k_1 - k_2) A_1 + k_2 A_2 = 0$$

$$-k_2 A_1 \sin \omega t + (k_2 A_2 - m_2 A_2 \omega^2) \sin \omega t = F_2$$

natural frequency has nothing to do with F_2

\(\therefore\) let $F_2 = 0$

$$\therefore \begin{bmatrix} m_1 \omega^2 - k_1 - k_2 & k_2 \\ -k_2 & k_2 - m_2 \omega^2 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

For $\omega = 10$ (rad/s)

$$\frac{A_1}{A_2} = \frac{1}{2} = - \frac{k_2}{(m_1 \omega^2 - k_1 - k_2)} = - \frac{k_2}{400 - k_1 - k_2} \dots \textcircled{5}$$

For $\omega = 10\sqrt{3}$ (rad/s)

$$\frac{A_1}{A_2} = \frac{1}{-2} = - \frac{k_2}{m_1 \omega^2 - k_1 - k_2} = - \frac{k_2}{1200 - k_1 - k_2} \dots \textcircled{6}$$

From $\textcircled{5}$ & $\textcircled{6}$

$$k_1 = 600 \text{ (N/m)}$$

$$k_2 = 200 \text{ (N/m)}$$

(ii) For $F = 10 \sin \omega t$.

$$\begin{bmatrix} m_1 \omega^2 - k_1 - k_2 & k_2 \\ -k_2 & k_2 - m_2 \omega^2 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 10 \end{bmatrix}$$

$$\Delta = \det \begin{bmatrix} m_1 \omega^2 - k_1 - k_2 & k_2 \\ -k_2 & k_2 - m_2 \omega^2 \end{bmatrix} = (4\omega^2 - 550) \cdot (150 - \omega^2) + 150^2$$

$$\Delta_1 = \det \begin{bmatrix} 0 & k_2 \\ 10 & k_2 - m_2 \omega^2 \end{bmatrix} = -10k_2$$

$$\Delta_2 = \det \begin{bmatrix} m_1 \omega^2 - k_1 - k_2 & 0 \\ -k_2 & 10 \end{bmatrix} = 10(4\omega^2 - 550)$$

$$A_2 = \frac{\Delta_2}{\Delta} = \frac{10(4\omega^2 - 550)}{(4\omega^2 - 550)(150 - \omega^2)} = 0$$

$$\therefore \omega = 11.726 \text{ (rad/s)}$$

5 (i) this is a two-degree of freedom problem

$$\left. \begin{aligned} \sum F_x &= L - kx - (x + e\theta)k = m\ddot{x} \\ \sum M &= M_0 - L \cdot a - (x + e\theta)k \cdot e = I\ddot{\theta} \end{aligned} \right\} \Rightarrow$$

$$25\ddot{x} + 2000x + 250\theta = L \quad \text{--- (1)}$$

$$2\ddot{\theta} + 62.5\theta + 250x = M_0 - 0.15L \quad \text{--- (2)}$$

(ii) $L(t) = 100 \sin(5t)$ $M_0(t) = 25 \sin(5t)$ --- (3)

let $x = A_1 \sin(5t)$ $\theta = A_2 \sin(5t)$ --- (4)

$$\ddot{x} = -25A_1 \sin(5t) \quad \ddot{\theta} = -25A_2 \sin(5t) \quad \text{--- (5)}$$

From (1) (2) (3) (4) (5)

$$A_1 = 0.0276$$

\therefore vertical vibration

$$x(t) = 0.0276 \sin(5t)$$